Identification of accident risks using a semantic web approach

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*Abstract***—***In the world, road accidents are one of the main causes of death, particularly for individuals between the ages of 5 and 29. The majority of them are the result of human error (drowsiness, unsafe overtaking, speeding, drunk driving, dangerous parking, etc.). Despite the development of smart autos and ontologies that explain semantic information, developing countries have yet to adopt IT solutions into their transportation management systems. To identify accident-prone zones, we evaluate accident data using a semantic web approach described in this article. The method is based on an ontology, and new information about accidents is obtained through descriptions and inferences.*

Keywords—traffic accident, ontology, ontology population, accident risks, semantic distance

I. INTRODUCTION

 Road traffic accidents are one of the main causes of death worldwide, particularly among persons aged five to 29. In 2016, road accidents killed 1.35 million people. Africa has the world's highest road accident mortality rate (26.6 per 100,000 inhabitants). In addition to the loss of human life, road accidents have a significant economic impact. According to the Senegalese Ministry of Transport, road insecurity costs at least 163 billion CFA francs annually, or 2% of GDP (gross domestic product).

 In response to the UN resolution on road safety, the WAEMU (West African Economic Monetary Union) issued Directive 14-2009CM-UEMOA, which aims to provide member nations with an information system on traffic accidents. Most impoverished countries, particularly those in West Africa, have yet to integrate information technology solutions into their transportation management systems. This situation is radically different from that of industrialized countries, which have changed their transportation networks in recent years with the introduction of intelligent transport systems (ITS). ITS is used in road and highway management, public transportation management, incident management, and other applications. They use the semantic web and ontologies to address the absence of semantics in information representation (accident descriptions) and inference.

 In this article, we present a semantic web approach to collect accident data and analyze it in order to identify accident-prone areas. The approach is based on an ontology with which descriptions are made and inferences are made to discover new knowledge related to accidents.

 The rest of the article is organized as follows. In section 2, we present a related work on methods for managing traffic accidents. In section 3, we present our web semantic approach by starting with the ontology construction that we populate in a second time. The examination of the results is addressed in section 4, where we interpret several graphs based on the data. We end by a summary and outlook.

II. RELATED WORK

 Traffic accidents, a major global concern, have sparked considerable and expanding academic interest. As a result, multiple approaches have been presented to develop efficient ways to limit the number of victims and damage caused by accidents.

 The main factor in these incidents is the driver's failure to accurately estimate and/or perceive the danger inherent in such scenarios [15]. Aoude Georges and al. [13] develop algorithms that use naturalistic data to evaluate inferred driver behaviors at crossings. It explains the various uses of the driver behavior inference problem for driver assistance systems. The two established kinds of algorithms are then introduced: a generative approach based on Hidden Markov Models (HMM) and a discriminative method based on Support Vector Machines (SVM). In [14] an incident detection system based on incident features and reporting traffic incident in a special intersection using machine vision algorithms is proposed. Vehicle detection is the first step in this process, which occurs after image sequences are obtained from the CCD camera's video image. The detection results will then be obtained by extracting event features such as the direction of moving vehicles, traffic flow, and the rate at which speed changes.

 Approaches based on graph theory, decision trees, neural networks and unsupervised learning are proposed. By comparing models stated using directed graphs with a model first developed by Peltzman, Roh and al. in [16] demonstrate how statistical methods based on directed graphs may be helpful in modeling traffic fatalities. They show that the directed graph model produces better out-of-sample forecasts than the original Peltzman model. An unsupervised method for traffic accident detection in first-person (camera mounted on the dashboard) recordings is presented in [17]. The method of detecting anomalies involves predicting the future locations of traffic participants and monitoring their prediction accuracy and consistency metrics using three different strategies. The

work in [18] uses Artificial Neural Networks and Decision Trees data analysis techniques to extract new insights from historical accident data. The study compares the performance of various Decision Tree algorithms and Artificial Neural Networks, analyzing data from a road accident data set. The results demonstrated that Decision Tree approaches outperformed Artificial Neural Networks, with a reduced error rate.

 Nonetheless, the lack of semantics in information representation (accident descriptions) and inference is addressed by web semantics and ontologies-based approaches. Ontologies allow self-driving cars to understand driving environments [19] and detect excessive speed in real time [20]. They enable the definition of relationships between autonomous vehicles [21], allowing for the regulation of intelligent vehicle circulation. The VEhicular ACcident ONtology (VEACON), designed to improve road safety, is described in [12]. The ontology incorporates data from the General Estimates System (GES) accidents database as well as information gathered at the time of an accident. Wang, J. and Wang, X. propose in [1] an ontology-based traffic accident risk mapping system. For risk mapping, the system considers the number and severity of accidents and describes them using a variety of criteria such as crash time, location, and environmental factors. However, the concept of accident risk is simplistic because it only considers the severity of accidents. [9] provides an ontology-based prototype framework for a traffic accident management system with a hierarchical structure. However, the suggested ontology only takes into consideration part of the elements involved in an accident, notably vehicles.

 However, ontology-based approaches must also address the challenge of populating because data often comes from diverse sources. The technique for semi-automatic matching in the ontology population is the main contribution of [2]. The proposed approach provides the system's users with a suitable idea list that is arranged according to a fitness value. Using natural language processing techniques, [4] suggests an approach for the ontology population that combines textual and visual information. A convolutional neural network is employed for the feature extraction task. Its foundation is a hierarchical system that employs semantic ontology layers and picture descriptors. The method in [10] uses automatic or semi-automatic procedures to add terms that describe the same thing or evoke similar situations to the domain ontology. The semi-automatic approach referred in [22] consists to extract knowledge from text using Natural Language Processing (NLP) techniques for language processing and semantic web techniques. The method in [11] is focused to the simultaneous insertion of semi-structured data based on semantic technology. The only data types processed are xml and tabular.

III. SEMANTIC WEB APPROACH PROPOSED

 The approach we propose is based on an ontology that must first be built and then populated with accident data. The use of this semantic web approach is justified by the fact that in transport information systems, a vehicle communicates with other vehicles, requesting information on road traffic. The driver of the vehicle, who can be a human driver or an autonomous agent, uses the information to decide the ideal route for a specific location. Ontologies are thus used to

create this coherence in transport systems. They make it possible to efficiently structure and encode the information collected by vehicle sensors, enabling interoperability between all agents involved in modern intelligent transport systems (ITS). Ontologies enable self-driving cars to understand driving environments [6] and detect speeding in real time [7]. They are used to define the relationships between autonomous vehicles [8], allowing for the regulation of intelligent vehicle circulation.

A. Ontology construction

In [5] we have built an ontology of road accidents describing the actors in different areas such as infrastructure, security, vehicles, health structures to which victims are transported, insurance, climatic factors, the media (mainly online media), economic impacts and psychology to understand certain driver behaviors. This ontology, of which Figure 1 shows the interactions between its elements, contains currently 530 axioms including 153 concepts and 30 object properties. With this ontology and the descriptions, inferences can be made in order to discover new knowledge related to accidents such as the main causes of accidents, the most accidental roads, drivers who commit more fatal accidents, and so on.

 To carry out this processing, the ontology must be populated with data initially coming from security agents, firefighters, witnesses or press articles. The following section presents the progress of this work.

Fig. 1. Interaction of ontological elements

B. Ontology population

 The process takes place in two phases: a data preprocessing phase and a processing phase*.*

1) Data source and preprocessing

 The processed data comes from various sources. They consist of accident reports carried out by security or emergency agents (police, gendarmerie, firefighters), witness reports or press articles. In each of these cases, the data is not

in the same format. We therefore need to transform these data sources into a common format in order to make the processing uniform. This standardization is done with deep learning techniques. Table 1 shows an example of a road accident report recorded by a gendarmerie officer. In this report, we are interested in the part which describes the circumstances of this accident. Information is recorded in a text which must be transformed to extract the useful data.

TABLE I. A ROAD ACCIDENT REPORT

 We represent the text as a graph by considering noun groups as nodes and verbs as edges. For this, we use the NLP techniques of [23]. Information extraction, machine translation, text correction, text identification, parsing, sentiment analysis, and other applications make use of NLP techniques. Here, we use a tokenizer that divides every sentence into words. Next, each sentence is tagged with partof-speech tags, which will be extremely useful in the following stage, entity recognition. In this stage, we look for mentions of potentially interesting entities within each sentence. Finally, we employ relation recognition to look for potential relationships between various items in the text.

Figure 2 shows the graph representing a part of the text in Table 1.

Fig. 2. Graph of a part of the text in Table 1

 In the next section, we will populate our ontology with the graph nodes.

2) Data processing

 To populate the ontology, we traverse the graph and for each relation we calculate its semantic distance [3] with a relation in the ontology. The nodes concerned are instances of the ontology when the distance is more than a certain threshold.

For each entity of the graph (N_i, E_k, N_j) corresponding to information in the report, we calculate the semantic distance with any relation (C_i, R_k, C_i) of the ontology by the following formula:

$$
sd(E_k, R_k) = \frac{(S_1 \cap S_2) + (G_1 \cap G_2)}{(S_1 \cup G_1) \cup (S_2 \cup G_2)}\tag{1}
$$

with: (S_1, S_2) respectively the synsets for the words (E_k, E_k) R_k) in the WordNet and (G_1, G_2) the gloss respectively for (S_1, G_2) $S₂$). $G₁$ and $G₂$ are obtained by splitting, removing stop words, lemmatization the synsets S_1 and S_2 . Synsets are a group of synonymous words that express the same concept.

The entities Ni and Nj will be added as instances to the concepts Ci and Cj when their semantic distance is the maximum of distances.

 On figure 3, we have the relations in our ontology. On the example of the figure 1, we obtain the result in table 2.

Fig. 3. Relations in our ontology

 By calculating the semantic distance between our ontology relations and the edge "driven by" of the graph in figure 2, we obtain the results in table 2.

TABLE II. SEMANTIC DISTANCE

| Edge on the graph | Relation in the ontology | Semantic distance |
|----------------------|---------------------------------|----------------------|
| driven by | belongs | 0,133 |
| driven by | belongs_to | 0,133 |
| driven by | causes | 0,071 |
| driven by | comes from | 0,117 |
| driven by | commits | 0,066 |
| driven by | concerns | 0,187 |
| driven by | consums | 0,066 |
| driven by | contains | 0,125 |
| driven by | evacuated | 0,062 |
| driven by | got into | 0,133 |
| driven by | has | 0.000 |
| driven by | having | 0,125 |
| driven by | includes | 0,250 |
| driven by | involves | 0,187 |
| driven by | is canceled | 0,222 |
| driven by | $\overline{1}$ is driven by | 0,444 |
| driven by | is evaluated on | 0,190 |
| driven by | is involved | 0,200 |
| driven by | $\overline{\text{is}}$ located | 0,157 |
| driven by | is noted by | 0,325 |
| driven by | is subscribed | 0,150 |
| driven by | is suspended | 0,157 |
| driven by | is written | 0,235 |
| driven by | occurred occording to | 0,185 |
| driven by | occurred during | 0,208 |
| driven by | occurred under | 0,190 |

Taking the maximum distance, nodes "van A" and "Mr Perrin" will be added as instances to concepts "Vehicle" and "Driver" respectively.

C. Ontology interrogation

 After populating the ontology, we use SPARQL queries to retrieve information from it. Figure 4 shows a query for determining accidents caused by a driver whose age is known.

SELECT ?accident WHERE { ?driver rdf:type ex:Driver. ?driver rdf:type ex:Person. ?driver rdf:type ex:Living_Being. ?driver ex:age ?age . $FILTER(2age = X)$. ?accident rdf:type ex:Accident. ?accident ex:causedBy ?driver . B

Fig. 4. Query for determining accidents caused by un given driver

Figure 5 represents a SPARQL query that provides the weather conditions under which an accident occurred.

SELECT ?weather_conditions WHERE { ?accident rdf:type ex:Accident. ?accident ex:occurredUnder ?wWather_conditions . ?Weather_conditions rdf:type ex:Weather_Conditions . B

In the following section, we will analyze and interpret the different results.

IV. RESULTS ANALYSIS

 The analysis of the data contained in the ontology makes it possible to discover new knowledge related to accidents such as the main causes of accidents, the most accidental roads, the drivers who commit more fatal accidents, the identification of victims of accidents and medical monitoring of the injured, etc. To determine the risks of accidents, we examine the data extracted from the ontology in this section. In figure 6 we study the accident risks in relation to the age of the driver. The following age categories are examined: (1) under 18, (2) between 18 and 24, (3) between 25 and 34, (4) between 35 and 44, (5) between 45 and 54, (6) between 55 and 64, and (7) above 65.

Fig. 6. The number of accidents in relation to the age of the driver

 The percentage of accidents involving drivers under the age of 18 is 3.92%; however, for drivers between the ages of 18 and 24, this number rises dramatically to almost 40%. For drivers between the ages of 25 and 34, we observe a minor decline to about 35%. Then, we observe a gradual decline to 12% for drivers between the ages of 35 and 44, 5% for drivers between the ages of 45 and 54, 1% for drivers between the ages of 55 and 64, and nearly nil for drivers beyond the age of 65.

 We also note that road accidents are linked to the state of the roads. In Senegal, as showed in figure 7, Though it may appear contradictory at first, the majority of accidents roughly 85% of cases occur on decent roads. Nonetheless, there are a number of explanations for this discovery. Firstly, especially in urban areas and on important highways, wellmaintained roads are frequently the busiest. Even with excellent road conditions, the increased traffic volume may raise the risk of accidents. Additionally, because they believe there is more safety, drivers may be enticed to drive faster on good roads. This may raise the possibility of collisions, particularly in places where speed limits are not observed.

Fig. 7. Accident instance in relation to the state of the roads

Apart from the state of the roads, climatic conditions have an impact on accidents. We will see in figure 8 how luminosity can influence accident cases and in figure 9 the atmospheric conditions.

Fig. 8. Impact of luminosity at the time of accidents

1 : broad daylight 2 : dawn 3 : dusk 4 : night 5 : well-lit road 6 : poorly lit road 7 : Absence of public lighting. 8 : indeterminate

 Approximately 70% of accidents happen during the day, 18% happen at night, and 7% happen after sunset. Dawn, well-lit or dark roadways, and other conditions make up the remaining percentages. The fact that there are more activities going on during the day, such traveling for work, education, or leisure, which increases traffic on the roads, helps to explain why accidents tend to occur during the day. Contrarily, dusk is a comparatively brief period of time, which helps to explain why fewer accidents occur during it than during night, which lasts longer.

Fig. 9. Impact of atmospheric conditions on accidents

1 : normal 2 : rain 3: fog 4 : dust cloud 5 : strong wind 6 : undetermined

 According to data, just approximately 5% of accidents happen when it rains, compared to more than 80% that happen during regular weather. This discrepancy can be partially attributed to Senegal's short rainy season, which lasts for only three months and does not include daily rain. Moreover, a low accident rate of approximately 3% is noted in situations involving alcohol. Senegal has a comparatively low rate of alcohol and drug usage when compared to other nations, which lowers the proportion of drunk driving accidents.

These following elements also promote accidents:

Loss of driver control;

- Faulty overtaking;
- Improper parking;
- Speeding;
- Failure to obey traffic signs;
- Speed bumps;
- Roaming animals;
- Lack of signage.

V. CONCLUSION

In this article, we present a semantic web approach to collect accident data and analyze it in order to identify accident-prone areas. The method relies on an ontology from which fresh information about accidents is discovered through descriptions and deductions.

In our future projects, we'll keep adding data from Senegalese online media outlets and police investigation reports to the ontology, enabling deduction in every traffic accident scenario. Subsequently, the ontology will be automatically populated in a second stage using accidentrelated image recognition. In order to justify the penalties to be applied to the at-fault drivers, we will look into Bayesian Networks, Markov Chains, and Propagation of Beliefs, among other concepts.

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